

4 Channel Uego System

The four channel Uego is a multichannel Uego system which enables monitoring of four Lambda channels simultaneously and is designed for individual cylinder tuning. Four analog 0-5V outputs are provided for logging and also RS232 and CAN bus interfaces.

USER MANUAL



Version 1.4

4 Channel Uego System wiring

All wiring is via a 36 way connector see pinout below. A 15 amp inline fuse is required on the 12V supply. Sensor heater grounds are connected to chassis ground.

Sensor 1

25 Vs+
13 Ip-
1 Ip+
26 Heater

Sensor 3

12 Vs+
24 Ip-
36 Ip+
33 Heater

RS232

3 Rxd
4 Txd
5 Gnd

0-5V Out

7 Channel 1
8 Channel 2
9 Channel 3
1 Channel 4
18 Signal ground

Sensor 2

27 Vs+
14 Ip-
2 Ip+
28 Heater

Sensor 4

11 Vs+
23 Ip-
34 Ip+
35 Heater

CAN bus

15 CAN High
16 CAN Low

Power Supply

20,21 +12V
6,19 Ground

VIEWED FROM BACK OF CONNECTOR



NTK Uego sensor

NTK Uego sensor has a eight pin connector but only 5 wires are required.

Sensor Wiring

Gray	Vs+
Black	Ip-
White	Ip+
Blue	Heater
Yellow	Heater ground

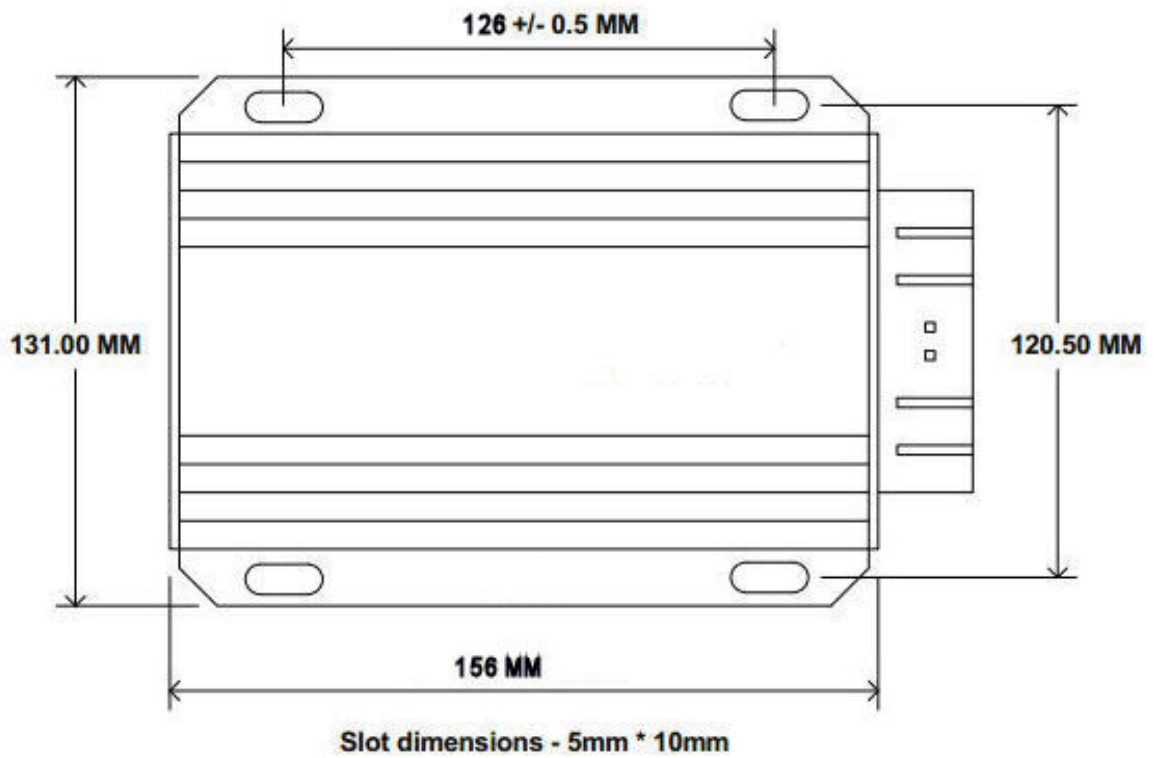


Note: the sensor contains a ceramic module and should not be subject to mechanical or thermal shock or it may be damaged.

DO NOT

- (1) Do not operate the sensor with high lead content fuels as this may reduce the sensor life to under 50 hours.
- (2) Influx of water into the exhaust will destroy the sensor if it is immersed.
- (3) Do not run the engine with the Uego sensor installed without power applied to the controller.

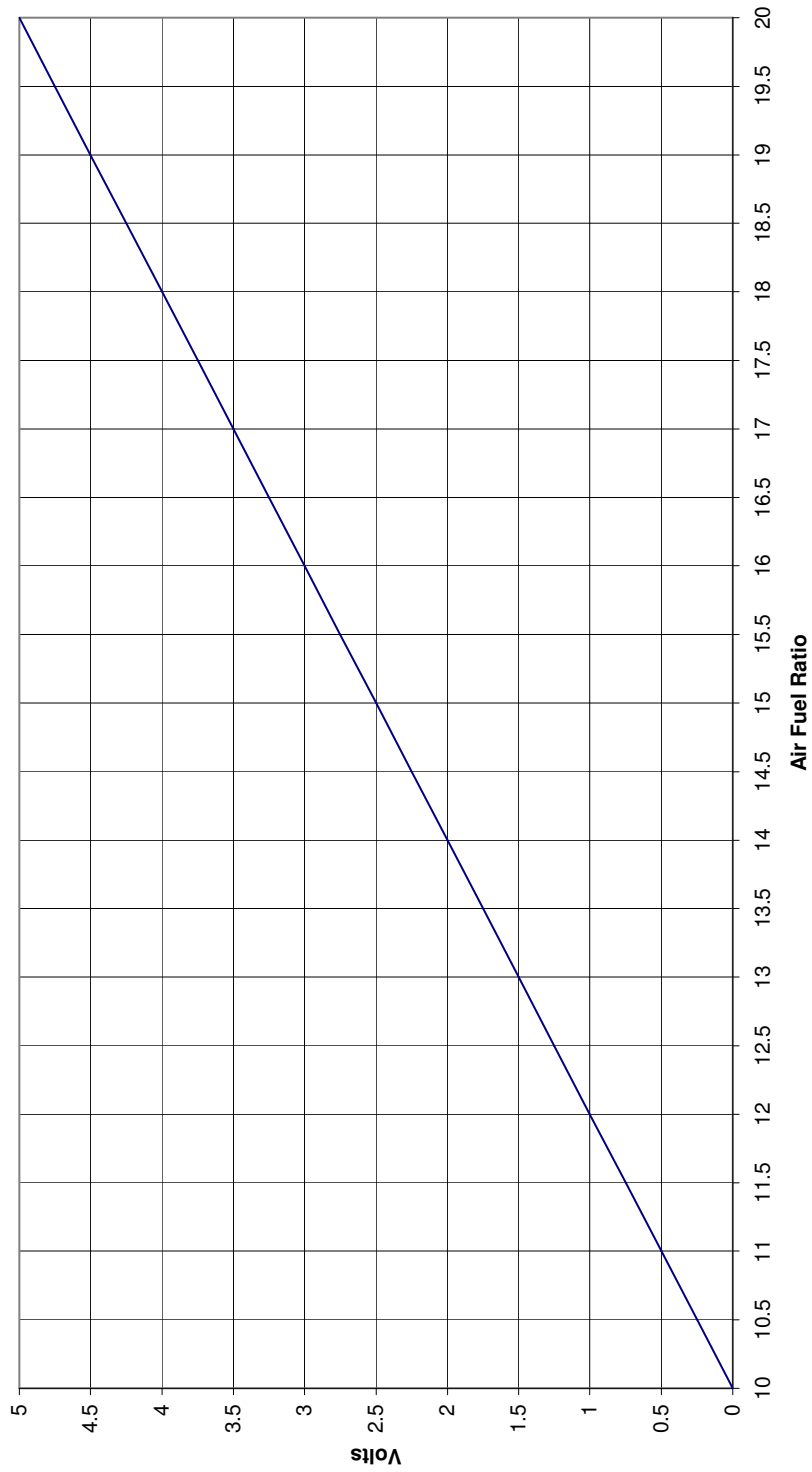
Case Dimensions



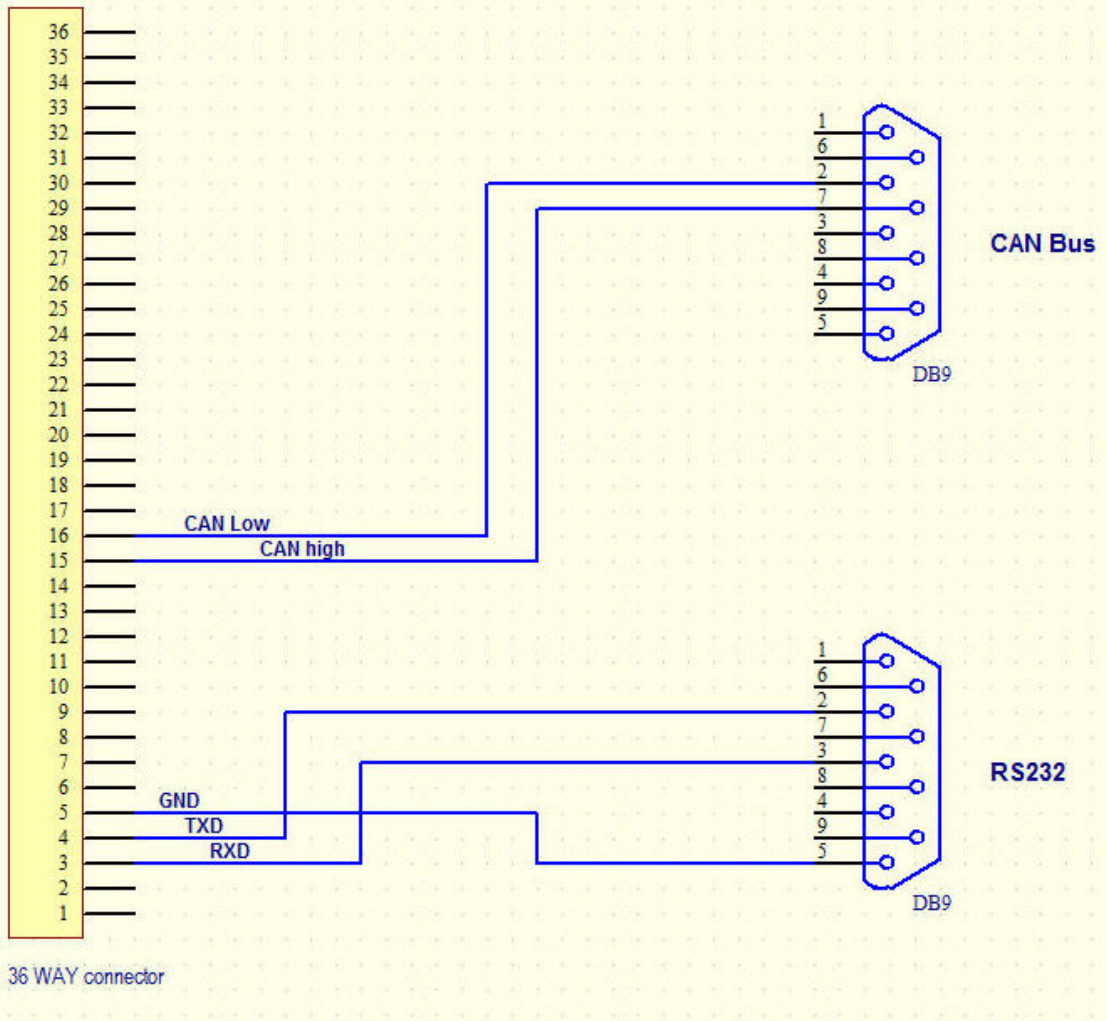
0-5V Output Scaling for Petrol AFR

$$\text{AFR} = (\text{volts} \times 2) + 10$$

M&W Uego Controller Analog Output



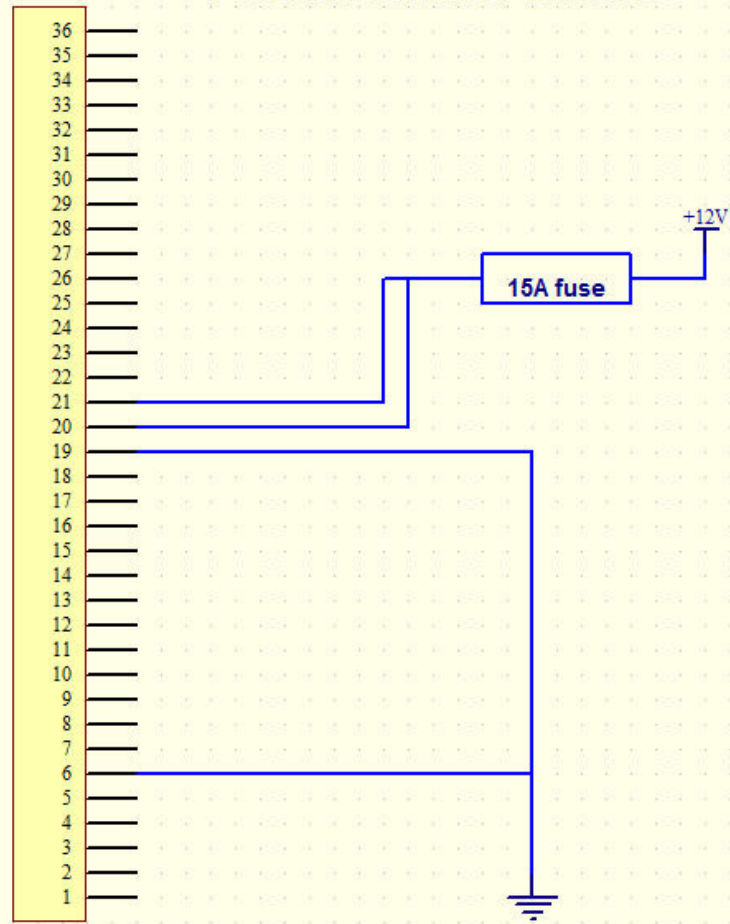
CAN Bus and RS232 wiring



VIEWED FROM BACK OF CONNECTOR



POWER SUPPLY WIRING



36 WAY CONNECTOR

VIEWED FROM BACK OF CONNECTOR



4CH UEGO CAN Data Format

The controller has two modes “warmup” or normal.

The 4CH UEGO uses two standard 8 byte CAN messages.

11 bit CAN address hex 041 (decimal 65) and hex 042 (decimal 66)

The packets are transmitted continuously every 50ms at 1Mbit/s.

Packet description

(Addr) hex 041 (decimal 65)

(bytes) 8

- (1) xx CH1 Lambda msb
- (2) xx CH1 Lambda lsb
- (3) xx CH2 Lambda msb
- (4) xx CH2 Lambda lsb
- (5) xx CH3 Lambda msb
- (6) xx CH3 Lambda lsb
- (7) xx CH4 Lambda msb
- (8) xx CH4 Lambda lsb

(Addr) hex 042 (decimal 66)

(bytes) 8

- (1)
- (2)
- (3)
- (4)
- (5) yy CH1 status byte
- (6) yy CH2 status byte
- (7) yy CH3 status byte
- (8) yy CH4 status byte

xxxx = Lambda x 1000 (ie. dec 650 = 0.650 lambda,
dec 1100 = 1.100 lambda, dec 1000 = 1.000 lambda)

yy = Status byte (ie. 00 = operating, 01 = warmup)

SPECIFICATIONS

CONTROLLER

Processor:

10 bit with CAN bus interface

Supply voltage:

12 to 15 volts DC (negative ground only) maximum 10 amps

Weight:

560 grams

Dimensions:

See drawing

Inputs:

4 X Uego sensor
1 X supply voltage (internal)

Outputs:

1 X RS232 port , 1 X CAN bus port
4 X 8 bit DAC 0-5 volt DC analog output

Measuring range:

0.68 to 1.36 Lambda

SENSOR

Type:

NGK LZA09-E1 wide range 5 wire sensor. (Exhaust temperature should not exceed 800°C)

Warmup time:

approx 30 seconds @ 25°C ambient

Weight:

85 grams

Heater Current 4 sensor:

5A at 12.8V typical warm, 9A peak at warmup with sensors at ambient temperature

Mounting:

M18 X 1.5 thread

NOTE: sensor is not rated for continuous operation on high lead content fuels. Operation in this mode may limit sensor life to under 50 hours.

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